## Lecture 32

CSE 331
Nov 16, 2016

## Talk today

## Buffalo Talks | How to crack the coding interviews?

Buffalo Talks has their next talk ready 4 Sal Vikneshwar, a theoretical computer science major at UB is going to talk about "How to crack the coding interviews?".
He has interviewed with tornes of companies and faled many times, but there were times when he didn't fall and got ofters from companies the Googit. Microsoft, Fb, etc. Sai is going to share all his experiences and how he did it. I assure you, Sa's talk will serve as a groat motivation for many of you who are currently in the interviewing process, so don't miss out on this ones.
Date and Tme - 11/16 (Wod) at $6: 00 \mathrm{pm}$
Venve - Knox 109

- An instructor (Atri hudra) thinkes this is a gaod note -


## High level view of CSE 331



Data Structures

Correctness+Runtime Analysis

## Greedy Algorithms

Natural algorithms


Reduced exponential running time to polynomial

## Divide and Conquer

Recursive algorithmic paradigm


Reduced large polynomial time to smaller polynomial time

# A new algorithmic technique 

Dynamic Programming

## Dynamic programming vs. Divide \& Conquer



## Same same because

Both design recursive algorithms


## Different because

Dynamic programming is smarter about solving recursive sub-problems


## End of Semester blues

Can only do one thing at any day: what is the optimal schedule to obtain maximum value?


## Write up a term paper

(10)

Party! (2)
Exam study (5)
331 HW (3)


## Previous Greedy algorithm



## Today's agenda

Formal definition of the problem

Start designing a recursive algorithm for the problem


## Property of OPT




## A recursive algorithm



## Exponential Running Time




## How many distinct OPT values?

## A recursive algorithm

M-Compute-Opt(j)

```
If j=0 then return 0
If M[j] is not null then return M[j]
M[j] = max { vi + M-Compute-Opt(p(j) ), M-Compute-Opt( j-1 ) }
return M[j]
```

> Run time = O(\# recursive calls)

## Bounding \# recursions

M-Compute-Opt(j)

```
If j = 0 then return 0
If M[j] is not null then return M[j]
M[j] = max { vi + M-Compute-Opt(p(j) ), M-Compute-Opt(j-1 ) }
return M[j]
```

Whenever a recursive call is made an M value of assigned

At most $n$ values of $M$ can be assigned


## Reading Assignment

Sec 6.1, 6.2 of [KT]


## When to use Dynamic Programming

There are polynomially many sub-problems


Richard Bellman
Optimal solution can be computed from solutions to sub-problems

There is an ordering among sub-problem that allows for iterative solution

