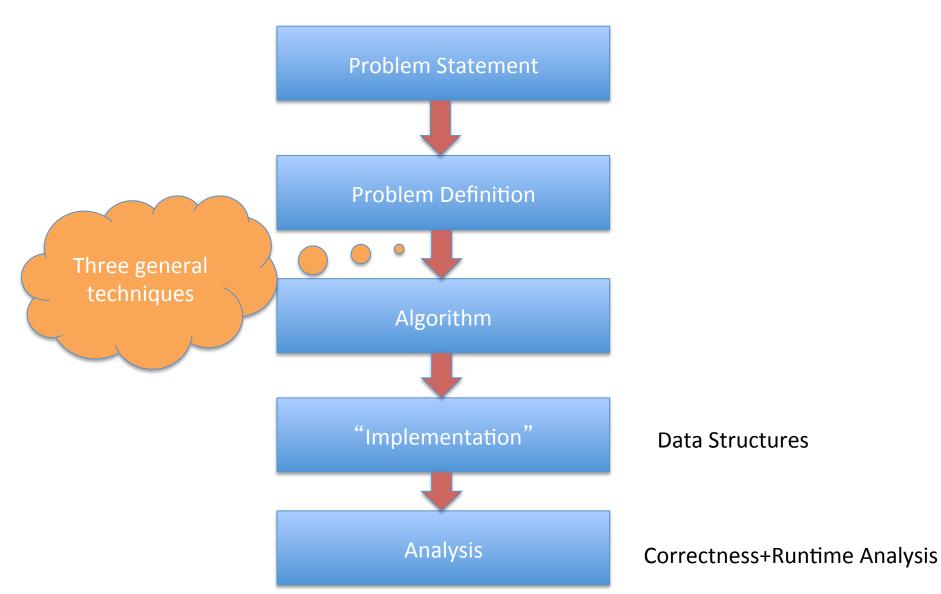
Lecture 32

CSE 331 Nov 16, 2016

Talk today

note 1	47 views
Buffalo Talks How to crack the coding interviews?	Actions *
Buffalo Talks has their next talk ready! Sai Vikneshwar, a theoretical computer science major at UB is going to talk about "F crack the coding interviews?". He has interviewed with tonnes of companies and failed many times, but there were times when he didn't fail and got offer companies like Google, Microsoft, Fb, etc. Sai is going to share all his experiences and how he did it. I assure you, Sai's talk will serve as a great motivation for many of you who are currently in the interviewing process, so do on this one. Date and Time - 11/16 (Wed) at 6:00 pm Venue - Knox 109	s from
- An instructor (Atri Rudna) thinks this is a good note -	
Updated 9 hours ago b	y Tim Weppner

High level view of CSE 331



Greedy Algorithms

Natural algorithms



Reduced exponential running time to polynomial

Divide and Conquer

Recursive algorithmic paradigm



Reduced large polynomial time to smaller polynomial time

A new algorithmic technique

Dynamic Programming

Dynamic programming vs. Divide & Conquer



Same same because

Both design recursive algorithms



Different because

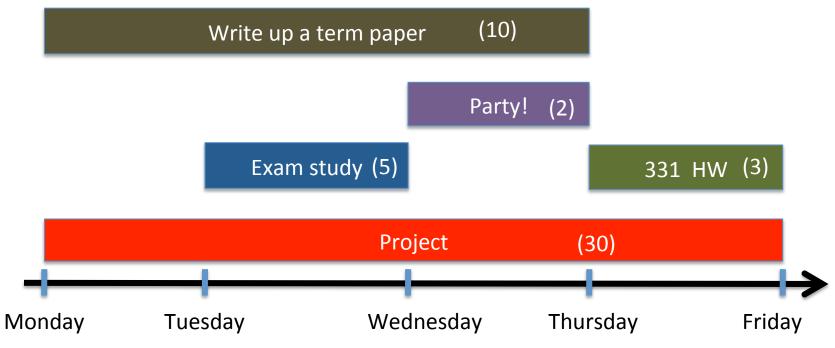
Dynamic programming is smarter about solving recursive sub-problems



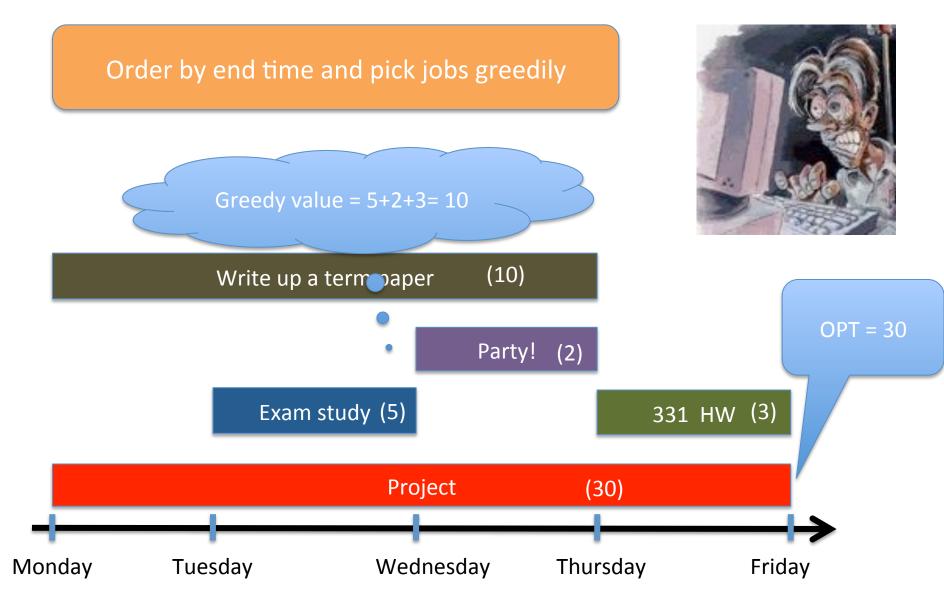
End of Semester blues

Can only do one thing at any day: what is the optimal schedule to obtain maximum value?





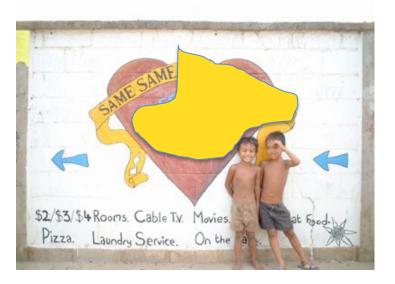
Previous Greedy algorithm



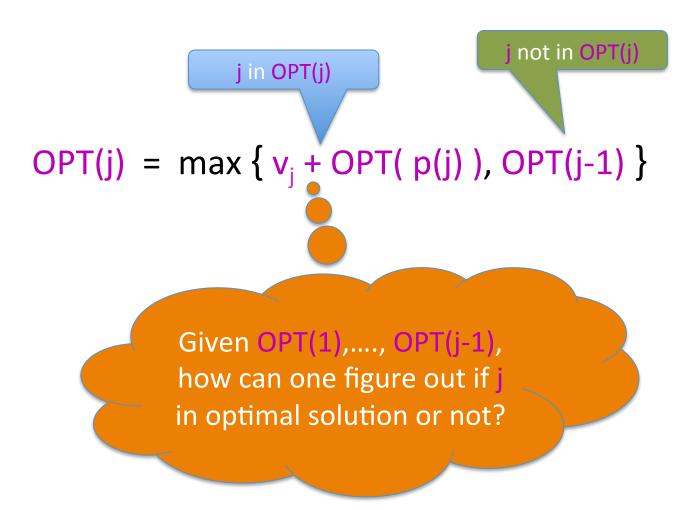
Today's agenda

Formal definition of the problem

Start designing a recursive algorithm for the problem

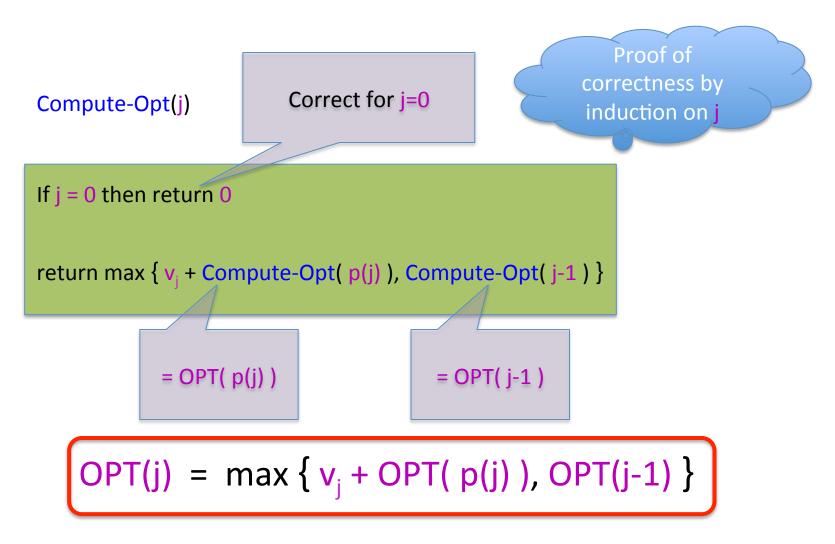


Property of OPT

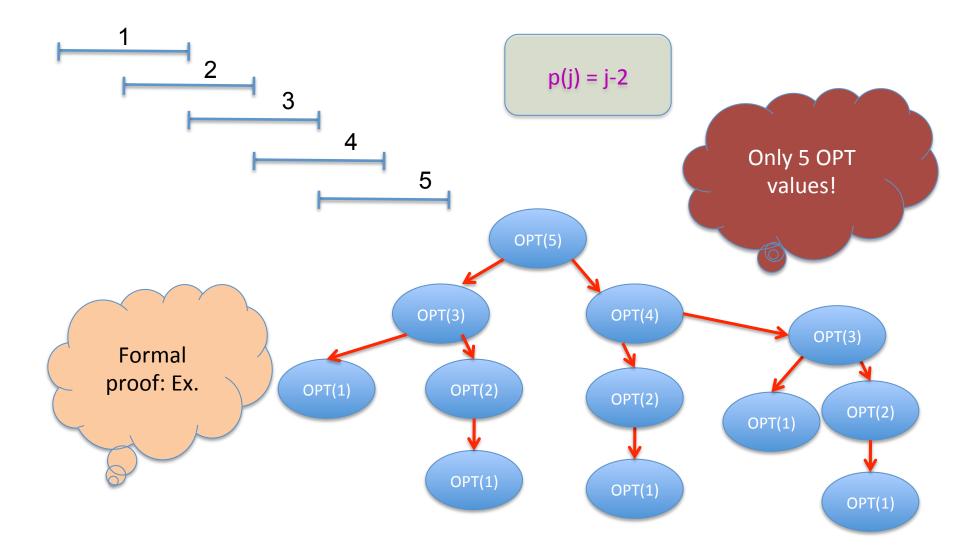




A recursive algorithm



Exponential Running Time





How many distinct OPT values?

A recursive algorithm

M-Compute-Opt(j)

M-Compute-Opt(j) = OPT(j)

If j = 0 then return 0

If M[j] is not null then return M[j]

M[j] = max { v_i + M-Compute-Opt(p(j)), M-Compute-Opt(j-1) }

return M[j]

Run time = O(# recursive calls)

Bounding # recursions



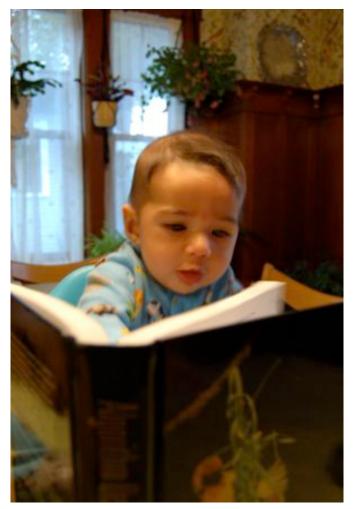
If j = 0 then return 0 If M[j] is not null then return M[j] M[j] = max { v_j + M-Compute-Opt(p(j)), M-Compute-Opt(j-1) } return M[j] Whenever a recursive call is made an M value of assigned

At most n values of M can be assigned



Reading Assignment

Sec 6.1, 6.2 of [KT]



When to use Dynamic Programming



There are polynomially many sub-problems

Richard Bellman

Optimal solution can be computed from solutions to sub-problems

There is an ordering among sub-problem that allows for iterative solution