

Lecture 33

CSE 331

Nov 18, 2016

Mini project video grading

note ☆ 0 views Actions

Mini project video grading

I apologize in advance for the fact that the grading of the mini-project will be a bit delayed. In particular, the top 10 videos who will get a chance to make a presentation for (potentially bonus points) might only get a few days of notice.

mini_project

[edit](#) - good note 0 Updated Just now by Atri Rudra

Homework 9

Homework 9

Due by **12:30pm, Friday, December 2, 2016**.

Make sure you follow all the [homework policies](#).

All submissions should be done via [Autolab](#).

Question 1 (Programming Assignment) [40 points]

</> Note

This assignment can be solved in either Java, Python or C++ (you should pick the language you are most comfortable with). Please make sure to look at the supporting documentation and files for the language of your choosing.

! Note on Timeouts

For this problem the total timeout for Autolab is 480s, which is higher than the usual timeouts of 180s or 240s in the earlier homeworks. So if your code takes a long time to run it'll take longer for you to get feedback on Autolab. **Please start early to avoid getting deadlocked out before the feedback deadline.**

Also for this problem, `C++` and `Java` are way faster. The 480s timeout was chosen to accommodate the fact that Python is much slower than these two languages.

HW 8 solutions

End of the lecture

Graded HW 6

Done by today

Apologies for the delay!

CS Ed week (Dec 5)



Celebrate
CSEDWEEK

with the Department of Computer
Science and Engineering at UB;

Children K-12 are invited to:

KID'S DAY

Monday, Dec. 5 | Davis Hall, UB

HANDS-ON ACTIVITIES, LIVE
DEMOS, ROBOTS & MORE!

Weighted Interval Scheduling

Input: n jobs (s_i, f_i, v_i)

Output: A schedule S s.t. no two jobs in S have a conflict

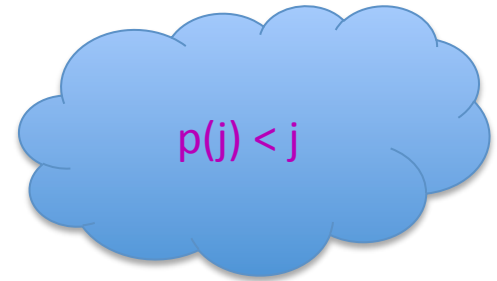
Goal: $\max \sum_{i \in S} v_j$

Assume: jobs are sorted by their finish time

Couple more definitions

$p(j)$ = largest $i < j$ s.t. i does not conflict with j

= 0 if no such i exists



$OPT(j)$ = optimal value on instance $1, \dots, j$

Property of OPT

j in $OPT(j)$

j not in $OPT(j)$

$$OPT(j) = \max \{ v_j + OPT(p(j)), OPT(j-1) \}$$

Given $OPT(1), \dots, OPT(j-1)$,
how can one figure out if j
in optimal solution or not?



A recursive algorithm

Compute-Opt(j)

Correct for $j=0$

Proof of correctness by induction on j

If $j = 0$ then return 0

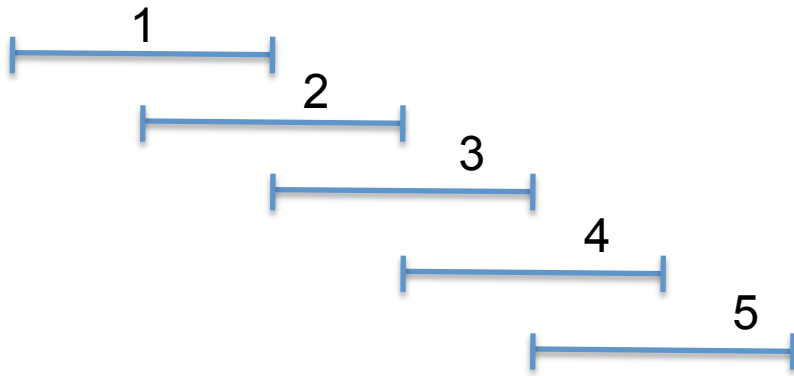
return $\max \{ v_j + \text{Compute-Opt}(p(j)), \text{Compute-Opt}(j-1) \}$

$= \text{OPT}(p(j))$

$= \text{OPT}(j-1)$

$$\text{OPT}(j) = \max \{ v_j + \text{OPT}(p(j)), \text{OPT}(j-1) \}$$

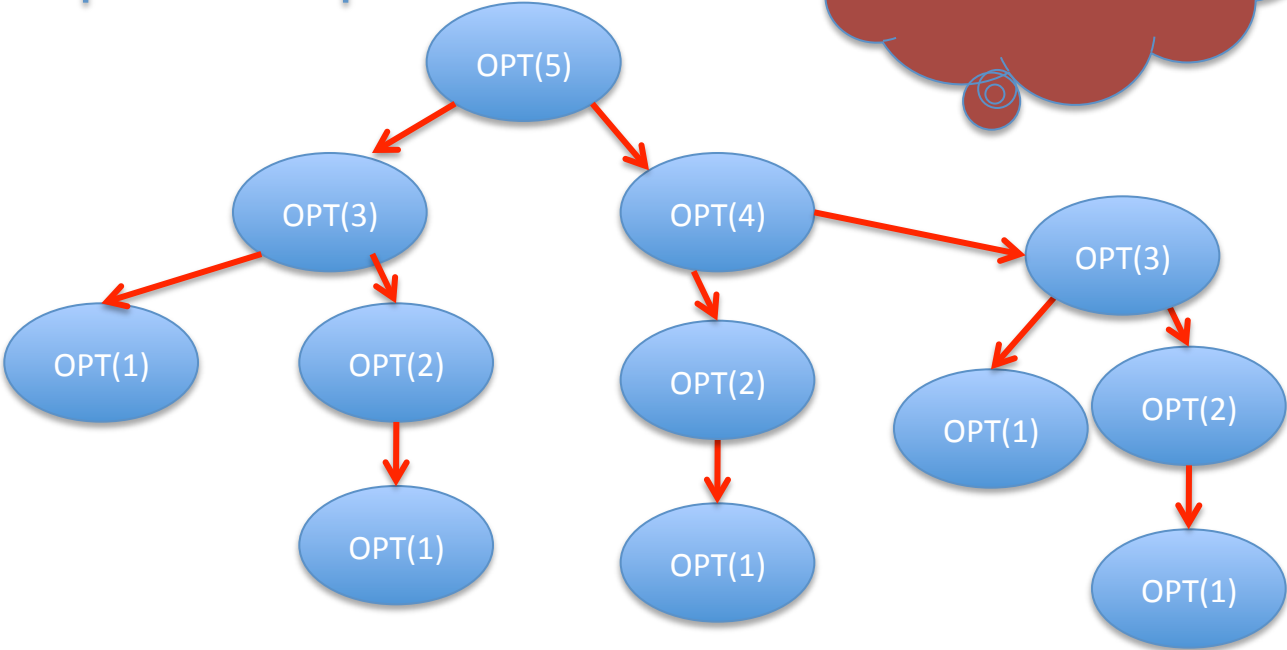
Exponential Running Time



$$p(j) = j - 2$$

Only 5 OPT values!

Formal proof: Ex.





Using Memory to be smarter

```
Pow (a,n)
```

```
⋮
```

```
// n is even and  $\geq 2$ 
```

```
return Pow(a,n/2) * Pow(a, n/2)
```

```
⋮
```

$O(n)$ as we recompute!

```
Pow (a,n)
```

```
⋮
```

```
// n is even and  $\geq 2$ 
```

```
t= Pow(a,n/2)
```

```
return t * t
```

```
⋮
```

$O(\log n)$ as we compute only once

How many distinct OPT values?

A recursive algorithm

M-Compute-Opt(j)

If $j = 0$ then return 0

If $M[j]$ is not null then return $M[j]$

$M[j] = \max \{ v_j + \text{M-Compute-Opt}(p(j)), \text{M-Compute-Opt}(j-1) \}$

return $M[j]$

M-Compute-Opt(j)
= OPT(j)

Run time = $O(\# \text{ recursive calls})$

Bounding # recursions

M-Compute-Opt(j)

If $j = 0$ then return 0

If $M[j]$ is not null then return $M[j]$

$M[j] = \max \{ v_j + \text{M-Compute-Opt}(p(j)), \text{M-Compute-Opt}(j-1) \}$

return $M[j]$

$O(n)$ overall

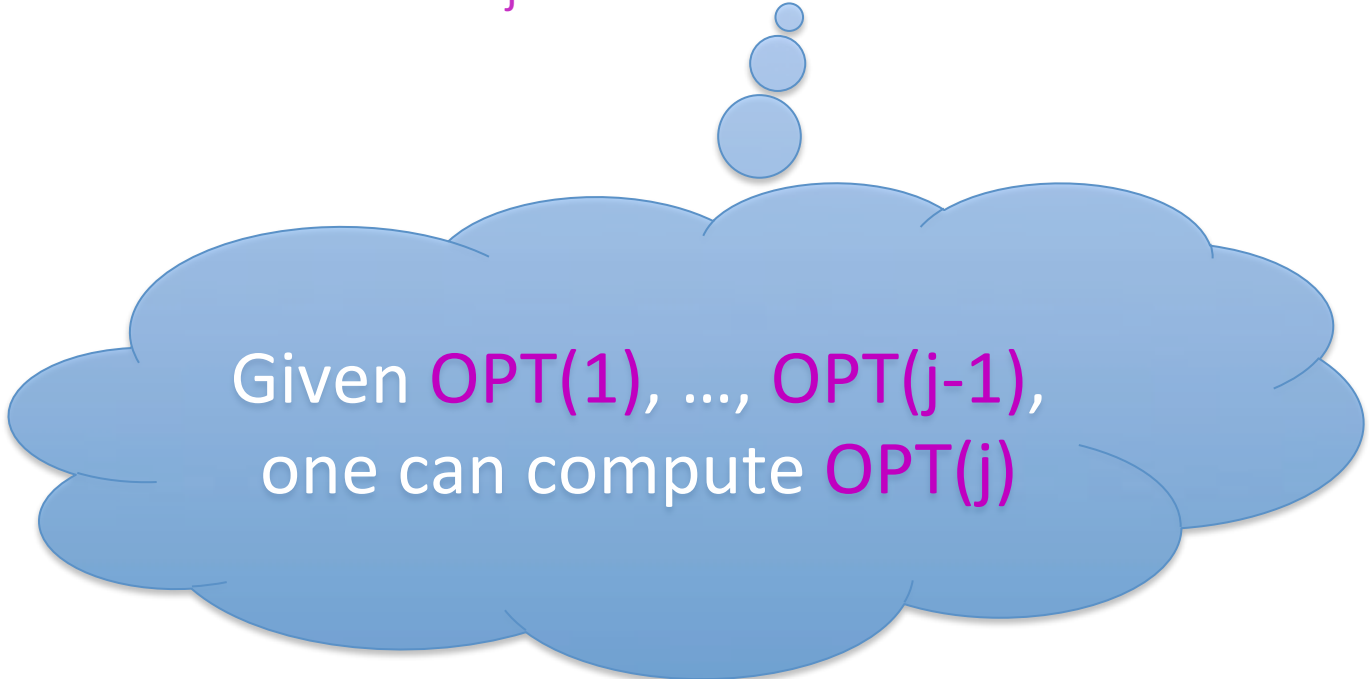
Whenever a recursive call is made an M value is assigned

At most n values of M can be assigned



Property of OPT

$$\text{OPT}(j) = \max \{ v_j + \text{OPT}(p(j)), \text{OPT}(j-1) \}$$



Given $\text{OPT}(1), \dots, \text{OPT}(j-1)$,
one can compute $\text{OPT}(j)$

Recursion+ memory = Iteration

Iteratively compute the OPT(j) values

Iterative-Compute-Opt

$M[0] = 0$

For $j=1, \dots, n$

$M[j] = \max \{ v_j + M[p(j)], M[j-1] \}$

$M[j] = \text{OPT}(j)$

$O(n)$ run time



Reading Assignment

Sec 6.1, 6.2 of [KT]



When to use Dynamic Programming

There are polynomially many sub-problems



Richard Bellman

Optimal solution can be computed from solutions to sub-problems

There is an ordering among sub-problem that allows for iterative solution